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Eigenvectors and Eigenvalues Cheat Sheet

An eigenbasis is a basis that is made up of eigenvectors of a matrix

We can create a **linear combination** of $\{\vec{u}, \vec{v}, \vec{w}\}$ by multiplying them by scalars α , β , and γ and adding them together:

$$
\begin{pmatrix}\nu_1 v_1 w_1 \\
u_2 v_2 w_2 \\
\vdots \\
u_n v_n w_n\n\end{pmatrix}\n\begin{pmatrix}\n\alpha \\
\beta \\
\gamma\n\end{pmatrix} = \alpha \begin{pmatrix}\nu_1 \\
u_2 \\
\vdots \\
u_n\n\end{pmatrix} + \beta \begin{pmatrix}\nv_1 \\
v_2 \\
\vdots \\
v_n\n\end{pmatrix} + \gamma \begin{pmatrix}\nw_1 \\
w_2 \\
\vdots \\
w_n\n\end{pmatrix}
$$
\n
$$
= (\vec{u} \ \vec{v} \ \vec{w}) \begin{pmatrix}\n\alpha \\
\beta \\
\gamma\n\end{pmatrix} = \alpha \vec{u} + \beta \vec{v} + \gamma \vec{w}
$$

where α , β , and γ must NOT all be zero (also called the "trivial" solution) \vec{u} \vec{v} \vec{w} α β γ $\beta|\vec{v}$ (ii \vec{v} \vec{w}) $\left(\beta\right)=\alpha\vec{u}+\beta\vec{v}+\gamma\vec{w}=0$ All sets of orthogonal vectors are linearly A set of vectors is $\{\vec{u}, \vec{v}, \vec{w}\}$ is **linearly dependent** iff: **linearly dependent** if one vector is equal to a linear combination of the other vectors $\gamma \overleftrightarrow{\mathbf{\psi}}$ αú independent If a set of vectors is *no*t linearly dependent, it is **linearly independent** The **vector space** that includes all real vectors of dimension n=2 is called \mathbb{R}^2 and can be plotted on a 2D grid The **vector space** that includes all real vectors of dimension n=3 is called \mathbb{R}^3 and can be plotted on a 3D grid If we take $\{\vec{u}, \vec{v}, \vec{w}\}$ for n=3, we get a set in \mathbb{R}^3 : \vec{v} = v_1 $v₂$ v_3 \vec{u} = u_1 u_2 u_3 \vec{w} = W_1 W_2 W_3 **Eigenvalues and eigenvectors** are An eigenvector \vec{u} does NOT Eigenvectors and eigenvalues are If you can create all vectors in a vector space V using a linear combination of $\{\vec{u}, \vec{v}, \vec{w}\}$: *V* is **spanned** by $\{\vec{u}, \vec{v}, \vec{w}\}$ u^1, v^1, w^1 = 1 0 0 , 0 0 1 , 0 1 1 spans \mathbb{R}^3 and is linearly dependent \rightarrow not a basis $\{\overrightarrow{u^2}, \overrightarrow{v^2}, \overrightarrow{w^2}\}$ = 1 0 0 , 0 0 1 , 0 1 Spans \mathbb{R}^3 and is 0 linearly independent \rightarrow is a basis If $\{\vec{u}, \vec{v}, \vec{w}\}$ is linearly independent and spans vector space V : $\{\vec{u}, \vec{v}, \vec{w}\}$ a **basis** of V w^i $W^{\overrightarrow{p}}$ $u^1 = u^2$ $\neq n$ This vector space is a subspace of \mathbb{R}^3 A vector space of dimension n can have exactly n linearly independent vectors in a set If we take $\{\vec{u}, \vec{v}, \vec{w}\}$ for n=2, we get a set in \mathbb{R}^2 : $\vec{v} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$ $v₂$ $\vec{u} = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$ u_2 $\vec{w} = \begin{pmatrix} W_1 \\ W_2 \end{pmatrix}$ w_2 This vector space is a subspace of \mathbb{R}^2 and a subspace of \mathbb{R}^3 Quantum superpositions are the same as linear combinations of the qubit energy states / basis $\ket{\psi}$ = (|0), |1 α $\begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \alpha |0\rangle + \beta |1\rangle$ We can create another qubit basis with equal superpositions of the energy states: $+$ = $\frac{1}{\sqrt{2}}$ $\frac{1}{2}$ |0 + $\frac{1}{\sqrt{2}}$ |1 >, |-> = $\frac{1}{\sqrt{2}}$ $\frac{1}{2}$ | 0 $\frac{1}{\sqrt{2}}$ | 1

Let's start by defining 3 vectors of length/dimension n: \vec{u} , \vec{v} , and \vec{w} :

$$
\vec{u} = \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{pmatrix} \quad \vec{v} = \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{pmatrix} \quad \vec{w} = \begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ w_n \end{pmatrix}
$$

We call this collection of vectors \vec{u} , \vec{v} , and \vec{w} a **set** of vectors, denoted as $\{\vec{u}, \vec{v}, \vec{w}\}$ A set of vectors is also called a **vector space**

The $\ket{0}$ and $\ket{1}$ quantum states we have been discussing all semester are eigenvectors of our quantum system's Hamiltonian matrix (!!!)

> σ_z also called the energy basis) This is why we measure in the Z-basis

sets of scalars (values) and vectors characteristic to a particular matrix and which satisfy:

change direction when

A single qubit can be described by a **vector space in** \mathbb{C}^2 where \mathbb{C}^2 contains all 2-dimensional complex vectors \mathbb{C}^2 is a Hilbert space

 $H\vec{u}=\lambda\vec{u}$ If multiple eigenvectors correspond to a single eigenvalue, the eigenvectors are linearly dependent

All finite-dimensional ($n \neq \infty$) vector spaces that have a meaningful inner product are Hilbert spaces

defined *relative* to a particular matrix

All vector spaces that can be mapped onto \mathbb{R}^n (including \mathbb{C}^n) are Hilbert spaces

i.e. an eigenvector for one matrix

$H\vec{u}=\lambda\vec{u}$ Where H is a matrix, λ is a scalar, and \vec{u} is a vector

may not be an eigenvector for a different matrix

- are orthogonal and thus linearly independent
- span \mathbb{C}^2
- are normalized

 $\{|+\rangle, |-\rangle\}$ are eigenvectors of σ_x \rightarrow are an orthonormal eigenbasis of σ_x

 $\{|0\rangle, |1\rangle\}$ are eigenvectors of σ_z \rightarrow are an orthonormal eigenbasis of σ_{z}

 $\{|0\rangle, |1\rangle\}$ are eigenvectors of both H and σ_{z}

The time-independent Schrodinger equation is the same as the eigenvalue/eigenvector equation:

 $H\overrightarrow{\Psi} = E\overrightarrow{\Psi}$

 \rightarrow the energies of these quantum states are equal to their eigenvalues $-\pi$ $-\pi/2$ 0 $\pi/2$ π Modified from Krantz et. al., Appl. Phys. Rev., 2019.

> Their eigenvalues correspond to the qubit energy levels

You can see there are more (actually an infinite number of) eigenvalues of higher energy, but we only care about the subspace spanned by $\{|0\rangle, |1\rangle\}$, which we call the **computational subspace**

We can represent
$$
\mathbb{C}^2
$$
 with two 2D graphs – one showing the real part of the vectors and one showing the imaginary part of the vectors

 $\sigma_z|\psi_{z+}\rangle = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$ $\binom{1}{0}$ =1 $\binom{1}{0}$ $\sigma_x|\psi_{x+}\rangle = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} \frac{\sqrt{2}}{2} \\ \frac{1}{2} \end{pmatrix} = 1 \begin{pmatrix} \frac{\sqrt{2}}{2} \\ \frac{1}{2} \end{pmatrix} = 1 \begin{pmatrix} +\rangle & \sigma_y|\psi_{y+}\rangle = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} \frac{\sqrt{2}}{2} \\ \frac{i}{2} \end{pmatrix} = 1 \begin{pmatrix} \frac{\sqrt{2}}{2} \\ \frac{i}{2} \end{pmatrix} \qquad \sigma_z|\psi_{z+}\rangle = \begin$ $\mathbf 1$ $\overline{2}$ $\mathbf 1$ $\overline{2}$ =1 $\mathbf 1$ $\overline{2}$ $\mathbf 1$ $\overline{2}$ $=1 |+\rangle$ $\sigma_y |\psi_{y+}\rangle = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$ $\mathbf 1$ $\overline{2}$ i % =1 $\mathbf 1$ % ' % $\sigma_x|\psi_{x-}\rangle = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ $\mathbf 1$ $\overline{2}$ $-\frac{1}{\sqrt{2}}$ =-1 $\mathbf 1$ $\overline{2}$ $-\frac{1}{\sqrt{2}}$ $= -1 \mid -\rangle$ $\sigma_y |\psi_{y-}\rangle = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$ $\mathbf 1$ $\overline{2}$ $-\frac{i}{\sqrt{2}}$ =-1 $\mathbf 1$ $\overline{2}$ $-\frac{i}{\sqrt{2}}$ $\sigma_z|\psi_{z-}\rangle = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$ $\binom{0}{1}$ =-1 $\binom{0}{1}$ =-1|1

 $\{|\psi_{x+}\rangle, |\psi_{x-}\rangle\}$, $\{|\psi_{y+}\rangle, |\psi_{y-}\rangle\}$, $\{ |\psi_{z+}\rangle, |\psi_{z-}\rangle \}$:

A **Hilbert space** is a type of vector space that has special properties that make it easy to define lengths and angles of its vectors (the inner product) and to perform calculus

Infinite-dimensional vector spaces have an additional constraint that they are "complete" – meaning (informally) that there are no gaps in the set of possible inner products

If $\{\vec{x}, \vec{z}\} \in V$, then *V* is NOT a Hilbert space

You can *always* assume you are in a Hilbert space in this course.

If a vector space is completely contained in another vector space, we call it a **subspace**

 $\{\vec{u}, \vec{v}\}$ is a subspace of $\{\vec{u}, \vec{v}, \vec{w}\}$

Mathematically: $\{\vec{u}, \vec{v}\} \subset \{\vec{u}, \vec{v}, \vec{w}\}\$